

QG series

QG65 analog H-series

QG65-KI-360H-AI-CM

Inclination sensor

1 axis vertical mounting

Factory programmable device

Output: 4 - 20 mA

Measuring range programmable
between 1° and 360°

Measuring range
Factory default: ±180°



General specifications 11377, v20210921

Housing	Reinforced plastic injection molded (Faradex DS, black, EMI shielded by stainless steel fiber in PC)
Dimensions (indicative)	60x50x27 mm
Mounting	Included: 4x M5x25 mm zinc plated steel pozidrive pan head screws, self-tapping (PZ DIN7500CZ) Mounting on flat surface only. Screw crosswise with maximum Torque 2.5 Nm
Ingress Protection (IEC 60529)	IP67, IP69K (with IP69K mating connector)
Relative humidity	0 - 95% (non condensing, housing fully potted)
Weight	approx. 110 gram
Supply voltage	10 - 30 V dc
Polarity protection	Yes
Current consumption	≤ 25 mA (excluding output signal)
Operating temperature	-40 .. +85 °C
Storage temperature	-40 .. +85 °C
Measuring range	Factory default: ±180°
Centering function	Yes (12 mA = 0°), range 360°
Frequency response (-3dB)	0 - 10 Hz
Accuracy (overall @20°C)	0,07° typ.
Offset error	± 0,03° typ. (± 0,08° max) after centering
Non linearity	± 0,06° typ., ± 0,1° 2σ, ± 0,15° max.
Sensitivity error	not applicable. Repeatability 0,05°
Resolution	0,01°
Temperature coefficient	± 0,005°/K typ.
Max mechanical shock	20.000g
Output	4 - 20 mA
Output load	Rload ≤ (50*Vs -300) (Ω) (Eg: Vs = 24 V: Rload ≤ 900 Ω)
Short circuit protection	Yes (T<55°C), Max 10 s (T>55°C)
Output refresh rate	20 ms
Programming options	Factory programmable (measuring range, filtering)

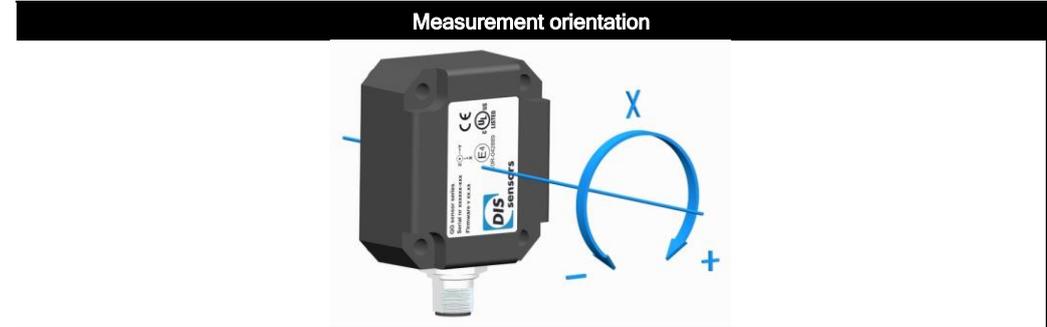
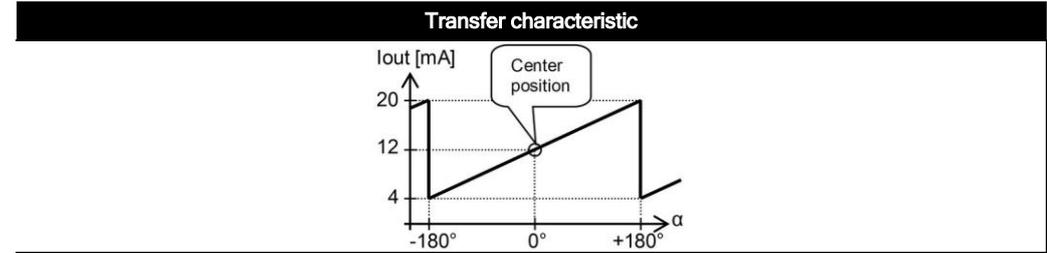
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$I_{out} = 12 + 8 \cdot (\alpha / 180)$ [mA]

Rotation in vertical plane.
Lateral tilt sensitivity error:
< $\pm 0,03^\circ$ lateral tilt (typ.)
Max. lateral tilt: 45°

Connection

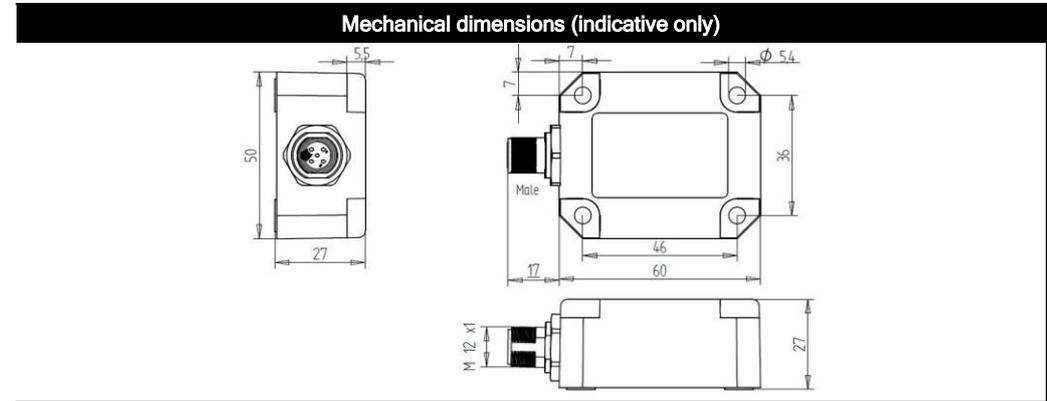
Wire / pin coding



Connectivity (cable length $\pm 10\%$)

M12 male 8p A-coding connector (Brass Nickel coated, contacts copper alloy)

Pin 1:	Output for factory use only	
Pin 2:	Supply voltage	
Pin 3:	for factory use only	
Pin 4:	for factory use only	
Pin 5:	Gnd	
Pin 6:	Centering input	
Pin 7:	Output	
Pin 8:	not connected	



Center function

Centering can be done to eliminate mechanical offsets. To execute centering connect center input to ground (>0,5sec) within 1 min. after power up. After centering you have 1 min. left for another centering. Normally the center input should be left unconnected.

Optional: for accurate mounting two factory mounted positioning pins can be mounted ($\varnothing 4$ mm) replacing 2x M5x25 mm.

As this device is accelerometer-based the sensor is inherent sensitive for accelerations/vibrations. Application specific testing must be carried out to check whether this sensor will fulfil your requirements.